

An (almost) optimal approximation scheme for minimum makespan scheduling

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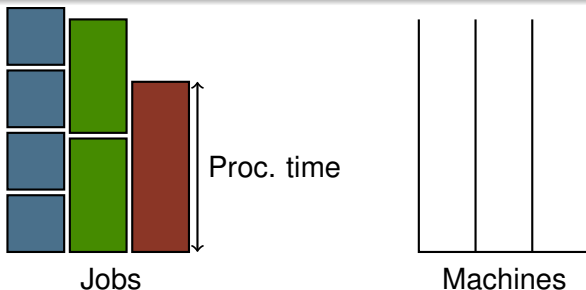
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Problem Definition

Minimum Makespan Scheduling

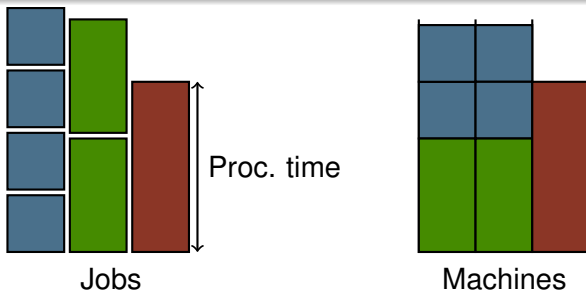
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- p_j : processing time job j .
- m machines.



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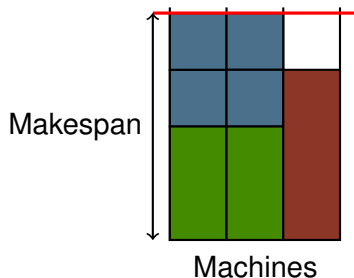
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Minimum Makespan Scheduling

- n jobs.
- p_j : processing time job j .
- m machines.
- Objective: Minimize makespan (maximum machine load).



What do we seek?

Theorem

*Determine the optimum solution is (strongly) **NP-hard**.*

→ Seeking poly-time (optimal) algorithms is unrealistic...

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An algorithm is *α -approximate* if for each instance I then

$$\text{cost}(\text{ALG}_I) \leq \underset{\substack{\downarrow \\ \text{approx. factor}}}{\alpha} \text{OPT}_I.$$

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Main Questions

- *Classic question:* What is the lowest approx factor achievable in poly-time?
- *Modern question:* Given an approximation factor, what is the best possible running time?

Classic Question

Definition

A family of algorithms $(\mathcal{A}_\varepsilon)_{\varepsilon>0}$ is a *Polynomial Time Approximation Scheme (PTAS)* if, for all $\varepsilon > 0$,

- \mathcal{A}_ε is a poly-time algorithm, and
- \mathcal{A}_ε is $(1 + \varepsilon)$ -approximate.

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Previous Literature

- A greedy algorithm is $4/3$ -approximate.

[Graham '66 + '69]

- There is a PTAS with running time $n^{\tilde{O}(\frac{1}{\varepsilon^2})}$.

[Hochbaum & Shmoys '87]

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Classic Question: Solved!

Modern Question

Reinterpretation: What is the best running time possible for a PTAS?

Known Algorithms

There is a PTAS with running time (roughly):

- $n^{\tilde{O}(\frac{1}{\epsilon^2})}$ [Hochbaum & Shmoys '87]
- $n^{\tilde{O}(\frac{1}{\epsilon})}$ [Leung '97]

- $2^{(\frac{1}{\epsilon})^{\tilde{O}(\frac{1}{\epsilon})}} + n$ [Alon et al. '98 & H. & S. '96]
- $2^{\tilde{O}(\frac{1}{\epsilon^2})} + n \log n$ [Jansen '10]

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Lower Bounds

- If $P \neq NP$, no PTAS can have a polynomial dependency on $\frac{1}{\epsilon}$ [Folklore]
- If the *Exponential Time Hypothesis* holds, there is no PTAS with running time $2^{(\frac{1}{\epsilon})^{1-\delta}} + n^{O(1)}$. [Chen et al. '13]

Our Main Result

Theorem

Minimum makespan scheduling admits a PTAS with running time

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General Strategy

General Scheme for designing a PTAS:

- 1 Round instance $\rightsquigarrow (1 + \varepsilon)$ multiplicative loss in objective.
- 2 Show that optimal solution of rounded instances has a “nice” structure.
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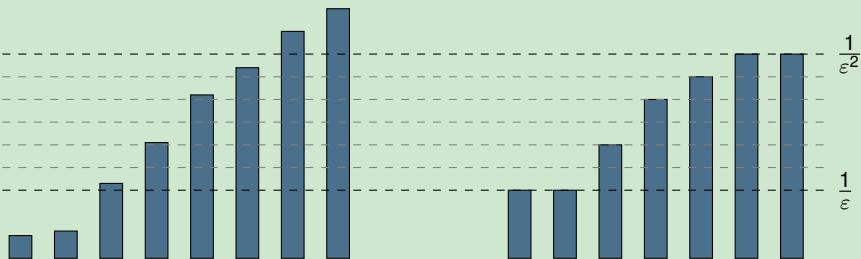
Rounding

Lemma

After rounding (and scaling) $OPT \in \{1, \dots, (2/\epsilon)^2\}$ and the sizes of jobs belong to a set P such that:

- $P \subseteq \{\frac{1}{\epsilon}, \frac{1}{\epsilon} + 1, \dots, \frac{1}{\epsilon^2}\}$ and,
- $|P| \leq \tilde{O}(\frac{1}{\epsilon})$.

Example



Let T be a guessed value for OPT .

Configurations

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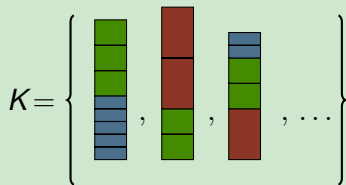
Configurations

A *configuration* is a one-machine schedule with total size $\leq T$.

Obs: If K is the set of all configurations, then

$$|K| \leq \left(\frac{2}{\epsilon}\right)^{|P|} = 2^{\tilde{O}(\frac{1}{\epsilon})}.$$

Example



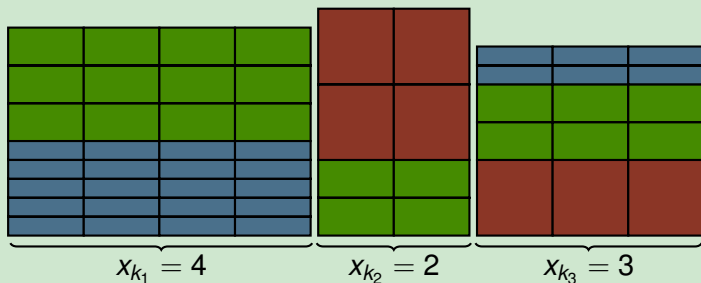
Compact description of a schedule

Multiple machines

We consider vector $(x_k)_{k \in K} \in \{0, \dots, m\}^{|K|}$, where

x_k : number of machines following configuration $k \in K$.

Example



Integer Programming Formulation

Observation

The vector $(x_k)_{k \in K}$ belongs to the system

$$\begin{aligned} \sum_{k \in K} x_k &= m \\ \sum_{k \in K} k_p x_k &= n_p \quad \text{for all } p \in P \\ x &\in \mathbb{Z}_{\geq 0}^K \end{aligned}$$

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of constraints: $\tilde{O}\left(\frac{1}{\varepsilon}\right)$
variables: $2^{\tilde{O}\left(\frac{1}{\varepsilon}\right)}$

Solving the IP: First Approach

Direct method [Alon et al. '98]

Use the following result:

Theorem (Kannan '87)

An integer program with d variables can be solved in time $2^{\tilde{O}(d)} s$ (where s is the length of the input).

In our case $d = |K| = 2^{\tilde{O}(\frac{1}{\epsilon})}$ and thus the running time is at least

$$d^d = 2^{2^{\tilde{O}(\frac{1}{\epsilon})}}$$

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If we only could decrease the number of variables...

Solving the IP: Second Approach

Guess the support [Jansen '10]

Theorem (Eisenbrand & Shmonin 2006)

A problem $\{c^t x : Ax = b, x \in \mathbb{Z}_{\geq 0}\}$

where A has h rows, admits an optimal solution x^* with

$$|\text{supp}(x^*)| \leq O(h \log(h + s)).$$

For our case:

- $h = |P| + 1 \approx \frac{1}{\epsilon} \log(\frac{1}{\epsilon})$, and
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Idea:

- 1 Try each possible support S : there are $\binom{|K|}{\tilde{O}(\frac{1}{\epsilon})} = 2^{\tilde{O}(\frac{1}{\epsilon^2})}$ many possibilities.
- 2 For each possibility solve the IP restricted to those variables with Kannan's algorithm.
- 3 Total running time: $2^{\tilde{O}(\frac{1}{\epsilon^2})}$.

Solving the IP: Third Approach

Understanding the Optimum

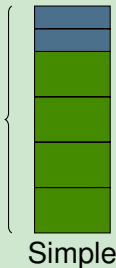
Definition

A configuration k is *complex* if contains more than $\log(1/\varepsilon^2)$ different sizes; o.w. is *simple*.

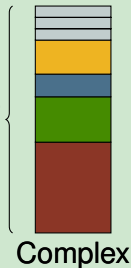
Example

$\leq \log(1/\varepsilon^2)$ sizes
(colors)

$$\log\left(\frac{1}{\varepsilon^2}\right) = 3$$



$> \log(1/\varepsilon^2)$ sizes
(colors)



Solving the IP: Third Approach

Understanding the Optimum

Definition (Informal)

A “subconfiguration” of a configuration k is called *maximal* if it contains all possible jobs of each taken size.

Example



Original
Configuration



Maximal
Subconfiguration



Non-Maximal
Subconfiguration

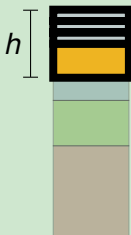
Lemma

Every complex conf. $k \in K$ contains two maximal subconfigurations k_1, k_2 s.t. the total size of k_1 and k_2 coincide.

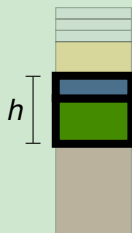
Example



Complex
Configuration k



Subconfiguration
 k_1



Subconfiguration
 k_2

Lemma

Every complex conf. $k \in K$ contains two maximal subconfigurations k_1, k_2 s.t. the total “size” of k_1 and k_2 coincide.

Proof.

- Let $C > \log \frac{1}{\epsilon^2}$ be the number of sizes (colors) in k .
- Number of maximal subconfigurations $2^C \geq \frac{1}{\epsilon^2}$.
- The total size of each configuration belongs to $\{1, 2, \dots, \frac{1}{\epsilon^2}\}$.
- \Rightarrow there must be two maximal subconfigurations of same total size.



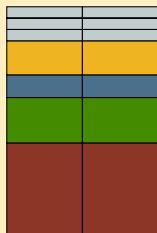
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Understanding the Optimum

Lemma (Sparsification Lemma (informal))

If a complex configuration is taken twice in a solution, then we can replace it by two other “less complex” configurations.

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| | |
|-------|-------|
| | |
| k_1 | k_1 |
| k_2 | k_2 |
| | |



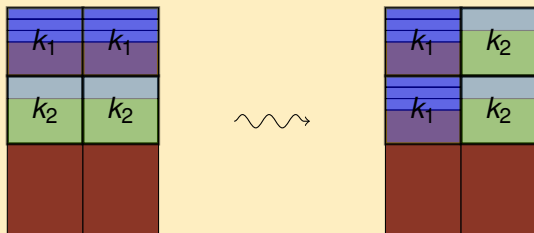
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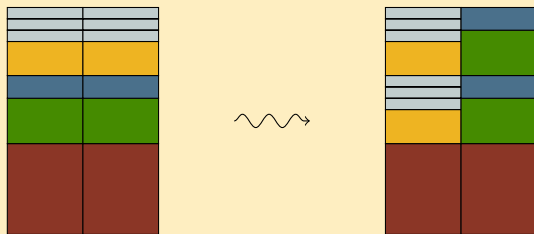
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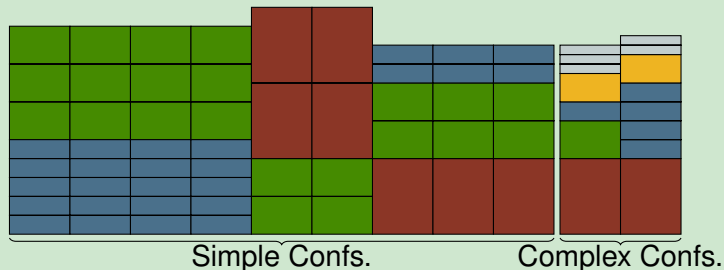
Understanding the Optimum

Theorem (Thin Solutions)

If the IP is not empty, then there is a solution x^* such that:

- At most $\tilde{O}(\frac{1}{\epsilon})$ machines get complex configurations
- Each complex configuration is used at most once
- $|supp(x^*)| \leq \tilde{O}(\frac{1}{\epsilon})$.

Example



Solving the IP: Third Approach

Solving the IPs

Part 1:

- 1 Guess jobs assigned to complex configurations, and number of complex machines.
- 2 Solve that subinstance optimally (with a Dynamic Program).

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Part 2: Remaining instance.

- 1 Guess the (simple!) configurations that x uses: there are $\binom{2^{\log^2(\frac{1}{\epsilon})}}{\tilde{O}(\frac{1}{\epsilon})} = 2^{\tilde{O}(\frac{1}{\epsilon})}$ many possibilities.
- 2 For each possibility solve the IP restricted to those variables with Kannan's algorithm.

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- 2 For each possibility solve the IP restricted to those variables with Kannan's algorithm.

Total running time: $2^{\tilde{O}(\frac{1}{\epsilon})}$

Summary of Results

- 1 The minimum makespan problem can be solved in time $2^{\tilde{O}(\frac{1}{\varepsilon})} + \text{poly}(n)$.
- 2 The result is best possible up to logarithmic factors in the exponent (assuming ETH).
- 3 Possibility to apply the same idea to other problems: in particular for the related machines makespan scheduling.